FIG. 1

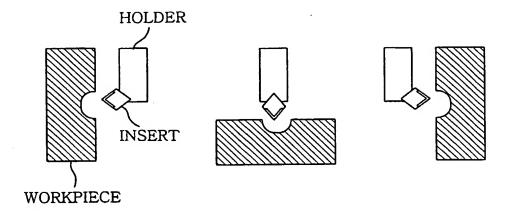


FIG.2A

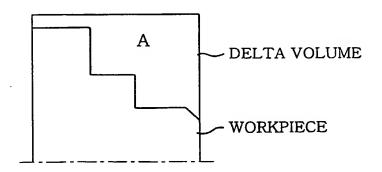


FIG.2B

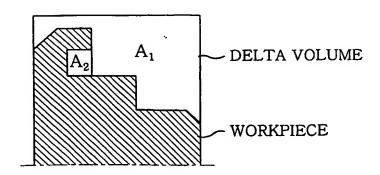


FIG.3

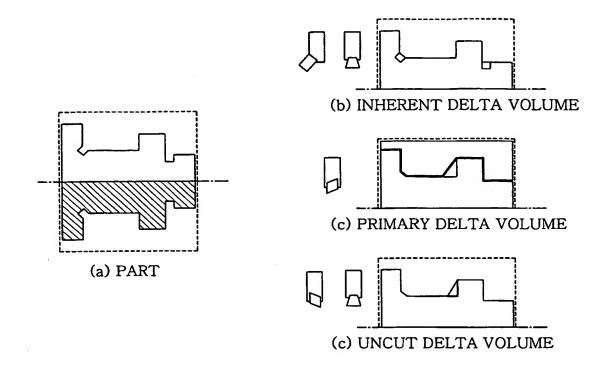
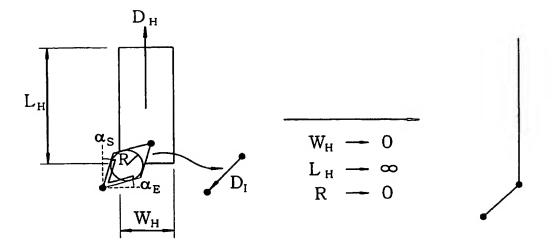


FIG.4



(a) TURNING TOOL

(b) ABSTRACT TURNING TOOL

 $\begin{array}{ll} D_H: \text{HOLDER DIRECTION} & R: \text{NOSE RADIUS} \\ L_H: \text{HOLDER LENGTH} & \alpha_S: \text{SIDE CUTTING EDGE ANGLE} \\ W_H: \text{HOLDER WIDTH} & \alpha_E: \text{END CUTTING EDGE ANGLE} \\ D_1: \text{INSERT DIRECTION} \end{array}$

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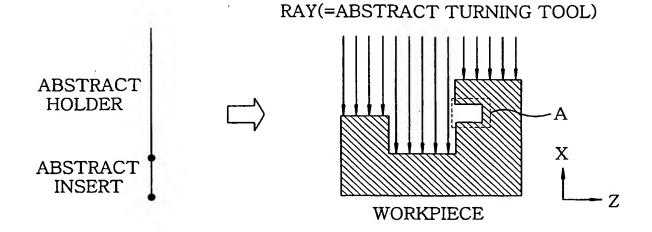


FIG. 6A

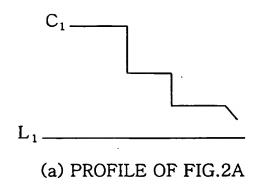
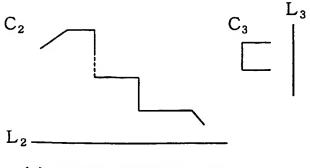


FIG.6B



(a) PROFILE OF FIG.2B

FIG.7A

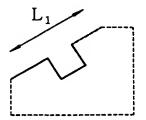


FIG.7B

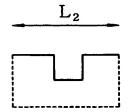


FIG.7C

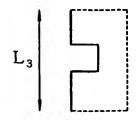


FIG.8

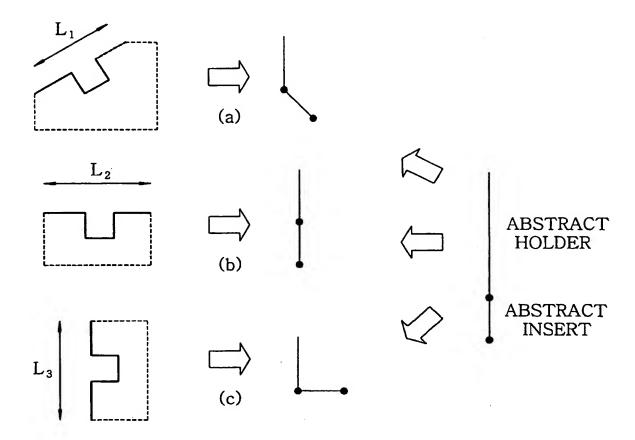


FIG. 9A

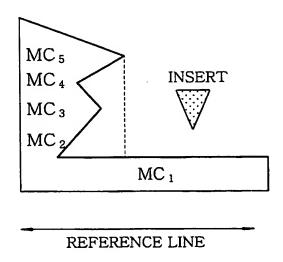
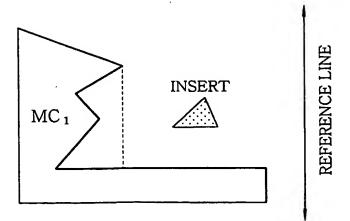
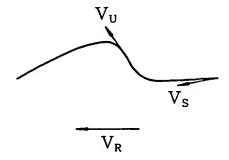


FIG.9B



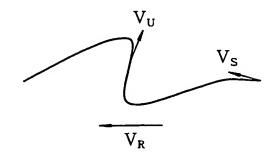
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FIG. 10A



 $SIGN (V_S \bullet V_R) = SIGN (V_U \bullet V_R)$

FIG. 10B



 $SIGN (V_S \bullet V_R) \neq SIGN (V_U \bullet V_R)$

FIG. 1 1A

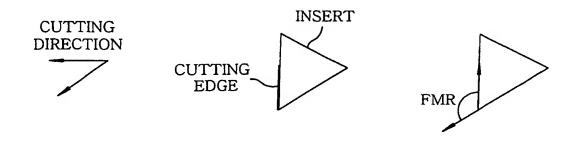


FIG. 11B

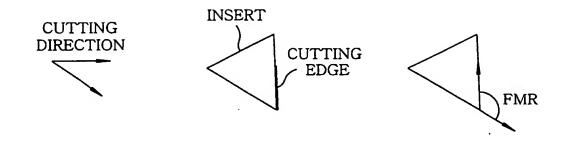


FIG. 11C

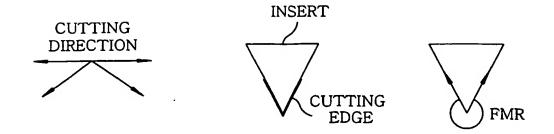
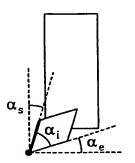
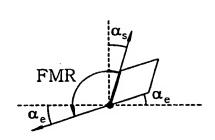


FIG. 12A





α_i: INSERT ANGLE

 α_S : SIDE CUTTING EDGE ANGLE α_e : END CUTTING EDGE ANGLE

FIG. 12B

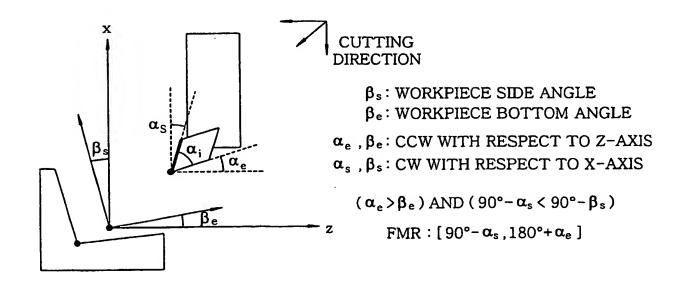


FIG. 13A

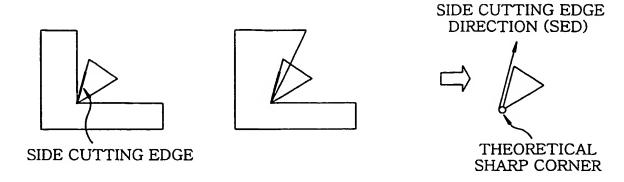


FIG. 13B

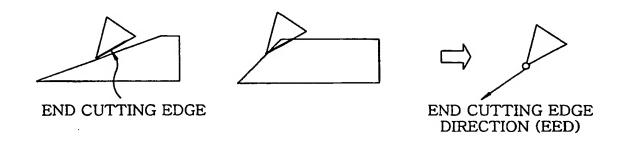


FIG. 14

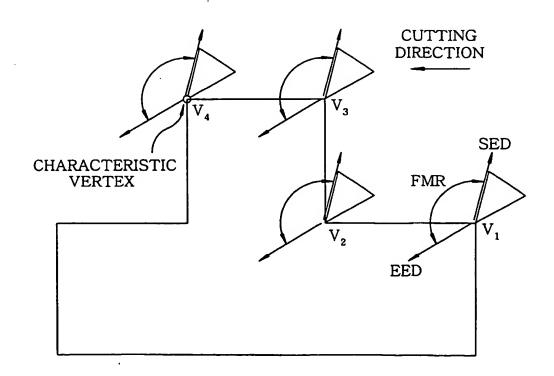


FIG. 15A

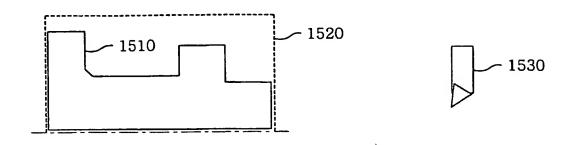


FIG. 15B

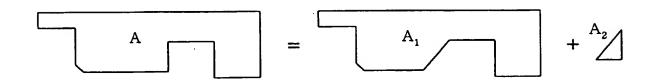


FIG. 16

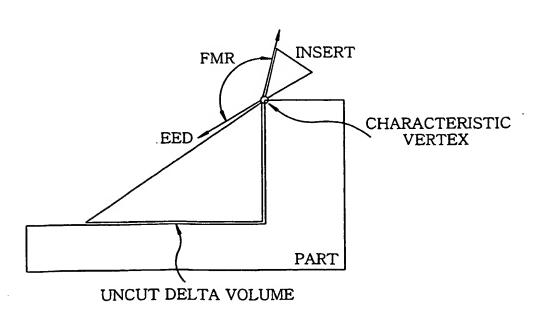


FIG. 17

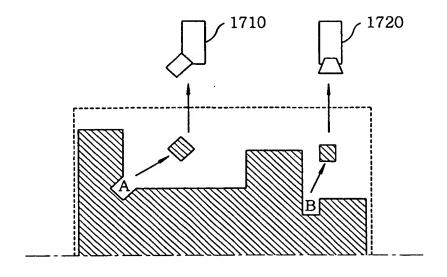


FIG. 18A

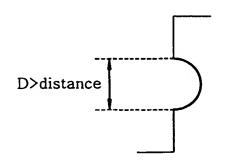


FIG. 18B

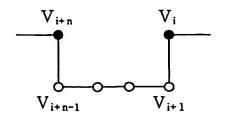


FIG. 19A

CUTTING DIRECTION

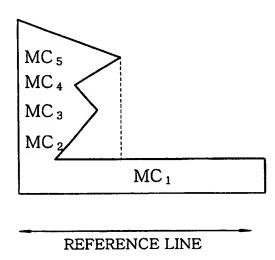


FIG. 19B

CUTTING DIRECTION RIGHTMOST CONVEX VERTEX MC 1 MC'1

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FIG.20A

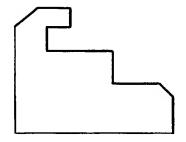


FIG.20B

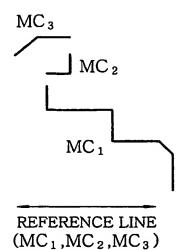


FIG.20C

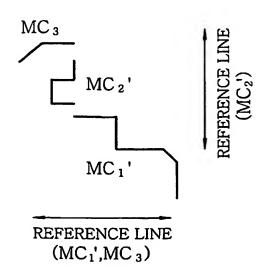


FIG.21A

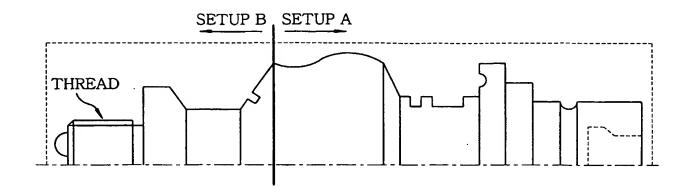


FIG.21B

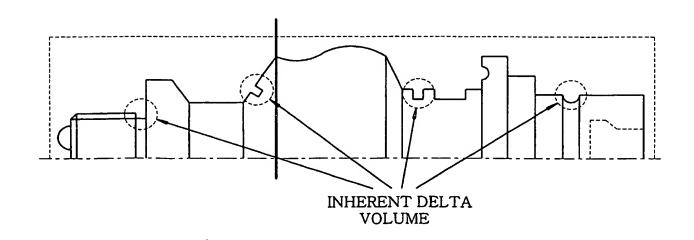


FIG.21C

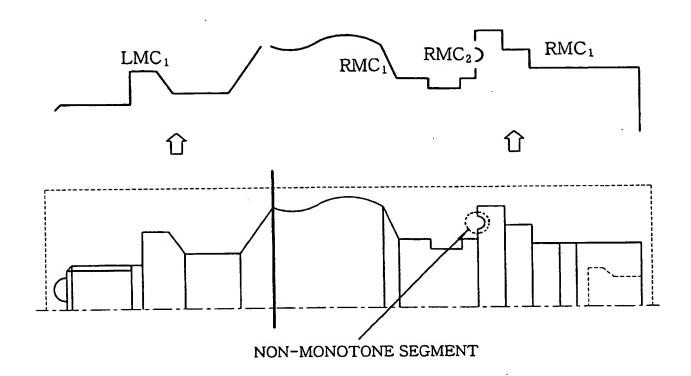
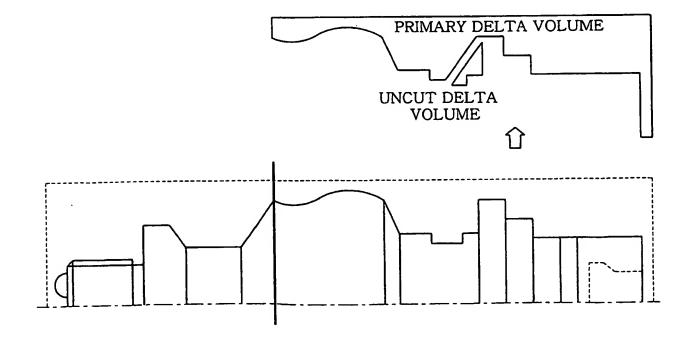


FIG.21D



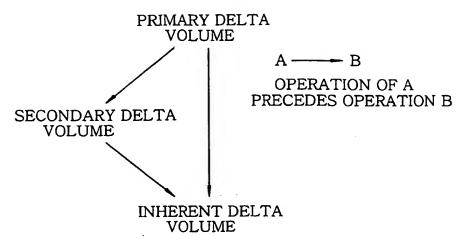


FIG.23A

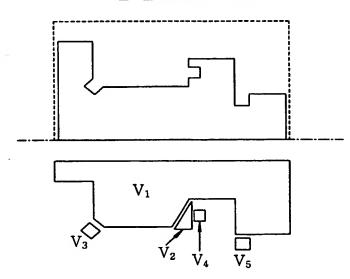


FIG.23B

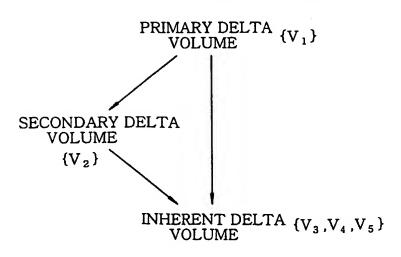


FIG.24

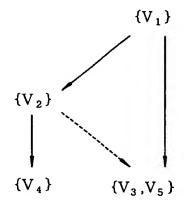


FIG. 25A

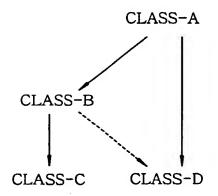
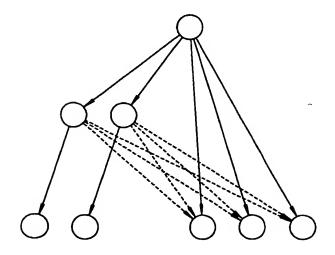


FIG.25B



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FIG.26A

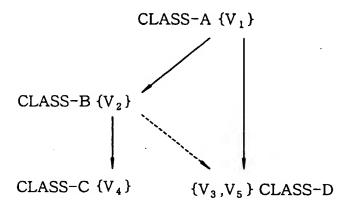


FIG.26B

G1:
$$V1 - V2 - SA \stackrel{V5}{\underbrace{V3}} JA$$

FIG.26C

G2:
$$V1 \longrightarrow SA \xrightarrow{V2 - V5} JA$$

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FIG.26D

G3:
$$SP < V2 \ V1' \ JP \longrightarrow SA < V2 - V5 \ V4 \ JA$$

FIG.26E

START — SO
$$\leftarrow$$
 $G1 \longrightarrow JO$ — END

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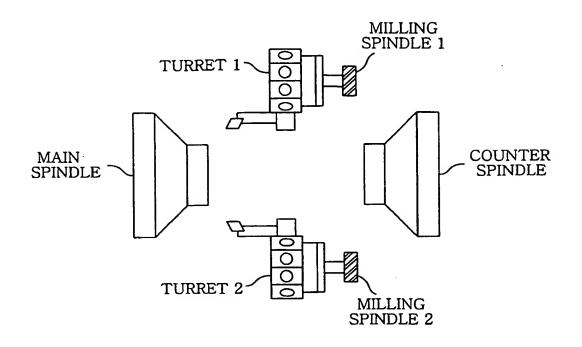
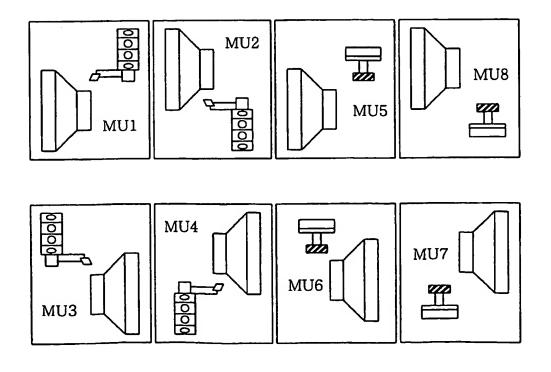


FIG.27B



TIME	5	10	8	2	. 2	15	10	5	5	8x2	3	3x4	2	2	2	2	2	5
PREDECESSOR	42	11	12	41 or 42	41 or 42	18	16	41	42	13	41 or 42	17	13	13	11	17	NONE	NONE
Op.DESCRIPTION	FACING	ROUGH CONTOURING	FINISH CONTOURING	GROOVING	GROOVING	ROUGH CONTOURING	FINISH CONTOURING	FACING	INNER CONTOURING	MILLING	MILLING	MILLING	GROOVING	GROOVING	GROOVING	GROOVING	CLAMPING (SETUP)	CLAMPING (SETUP)
FEATURE #	1	2	2	က	4	5	5	9	7	8,9	10	12,13,14,15	16	17	18	19	NONE	NONE
OPERATION #	11	12	13	14	15	16	17	18	21	31-1,31-2	33	32-1,32-2, 32-3,32-4	22	23	24	25	41	42

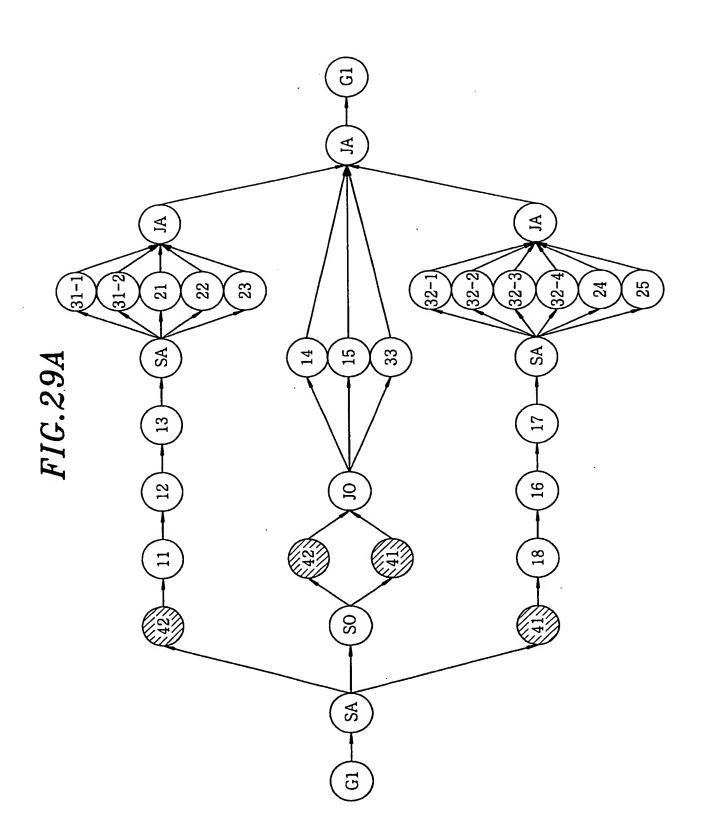
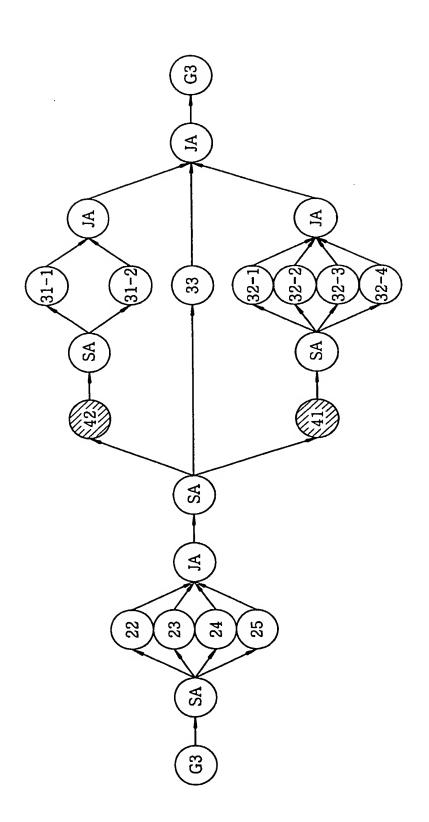


FIG.29B



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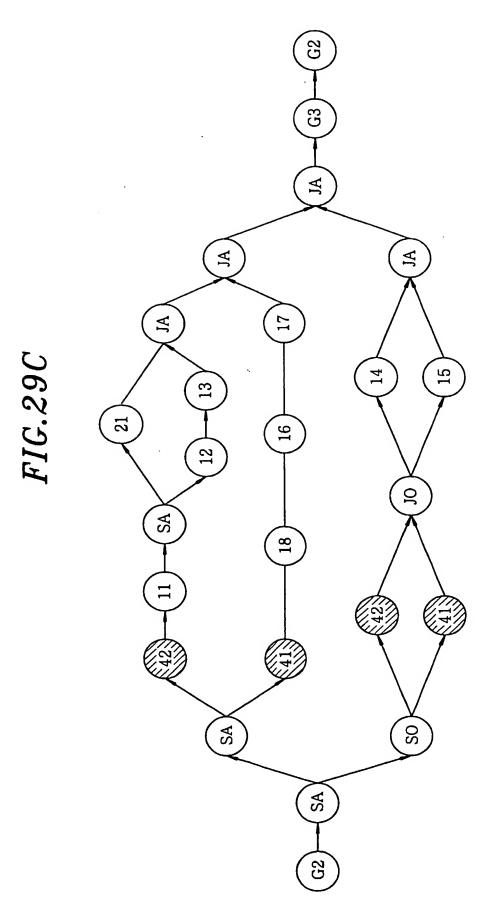


FIG.29D

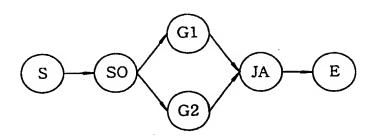


FIG.30

TIME	16		12 13 21		32-1,32-2,32-3,32-4	31-1,31-2
	16		12			
-	18	1 4	11	15		
MU	MU1	MU2	MU3	MU4	MU5	MU6

FIG. 31A

FIG. 31B

TOLERANCE: ± 0.1

TOLERANCE: ± 0.1

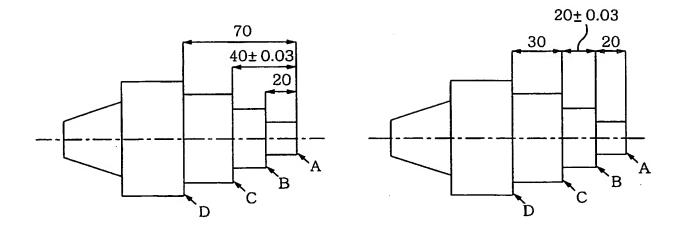
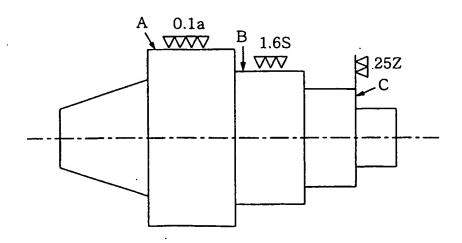


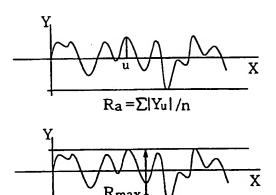
FIG.32



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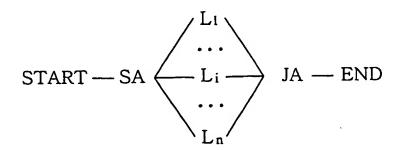
FIG.33

Ra	R_{max}	R_z	symbol	
0.013a	0.05S	0.05Z		
0.025a	0.1S	0.1Z		
0.05a	0.2S	0.2Z	∇	
0.10a	0.45	0.42		
0.20a	0.8S	0.82		
0.40a	1.6S	1.62		
0.80a	3.2S	3.2Z		
1.6a	6.3S	6.3Z		
3.2a	12.5S	12.5Z		
6.3a	25S	25Z	$\overline{\nabla}$	
12.5a	50S	50Z		
25a	100S	100Z		





R_z=(sum of 5 maximum Ys - sum of 5 minimum Ys)/5



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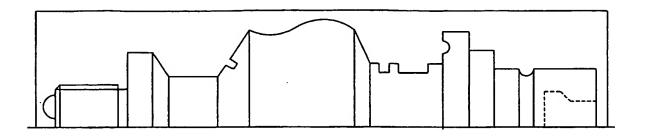


FIG.35B

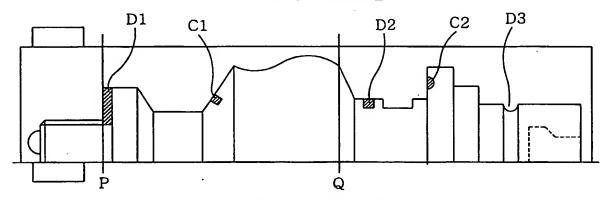
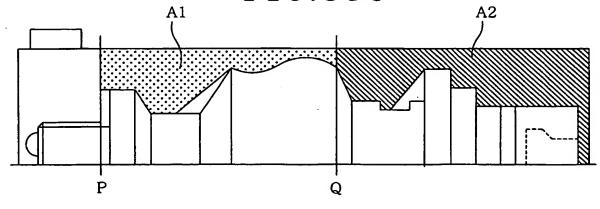
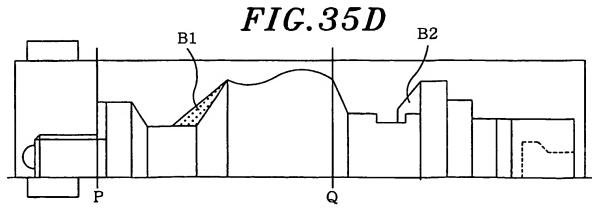


FIG.35C





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FIG. 35E

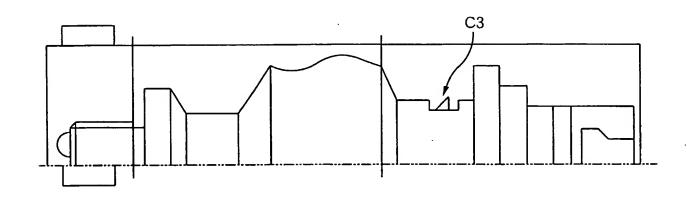


FIG.35F

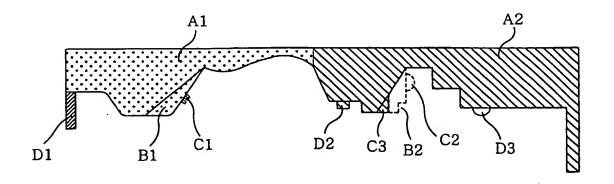


FIG. 36A

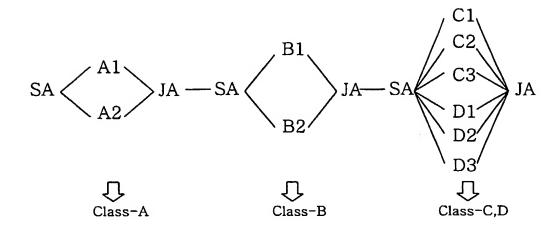
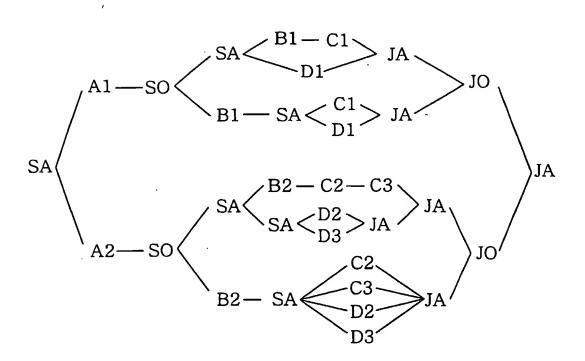


FIG. 36B



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FIG. 36C

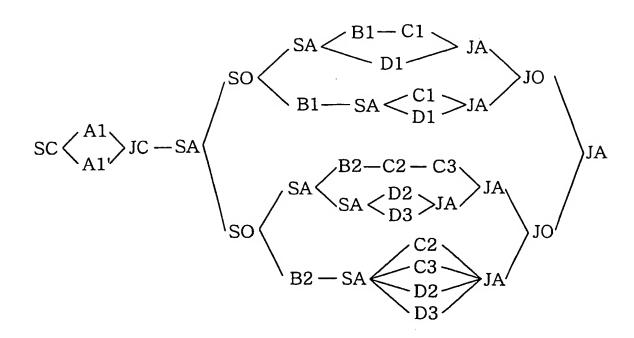


FIG.36D

$$START - SO \stackrel{PSG 1}{\longleftarrow} JO - END$$

$$PSG 3$$

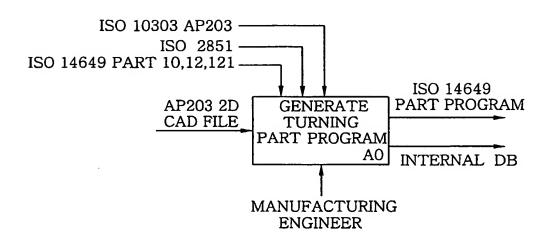
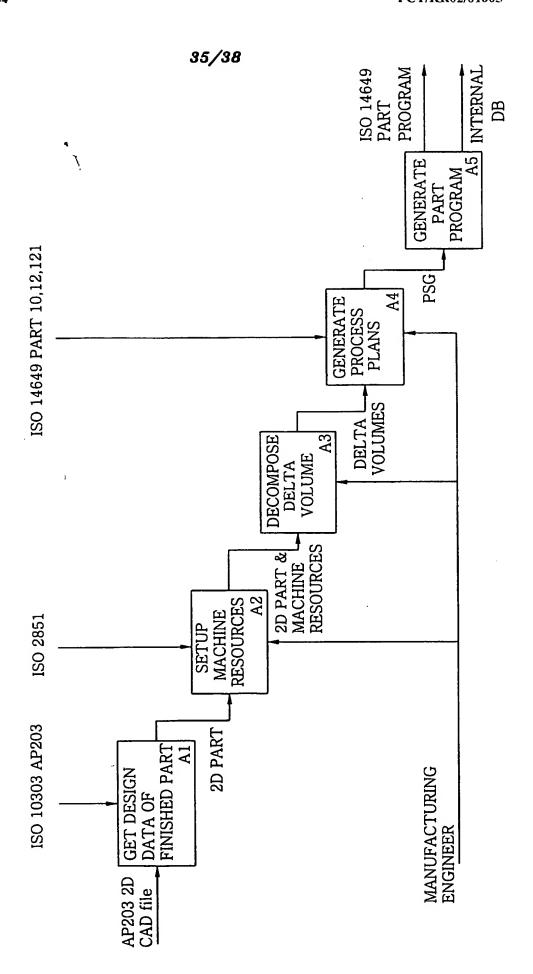


FIG.38



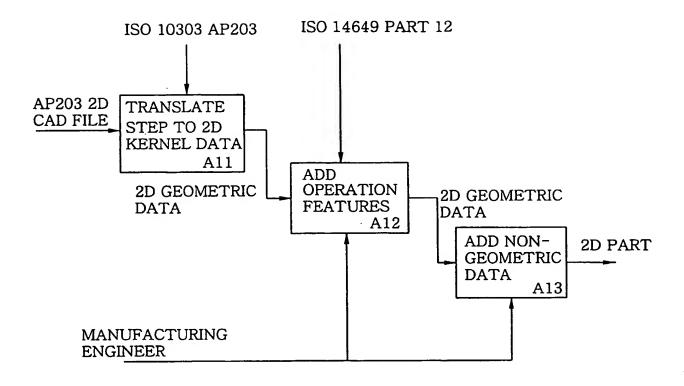
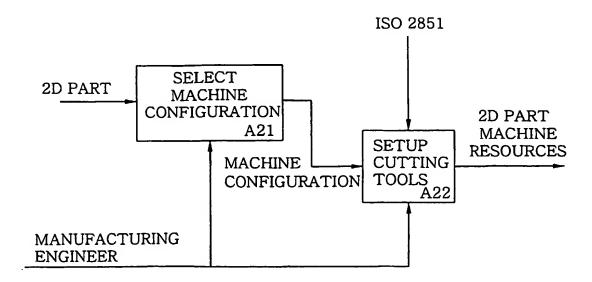


FIG. 40



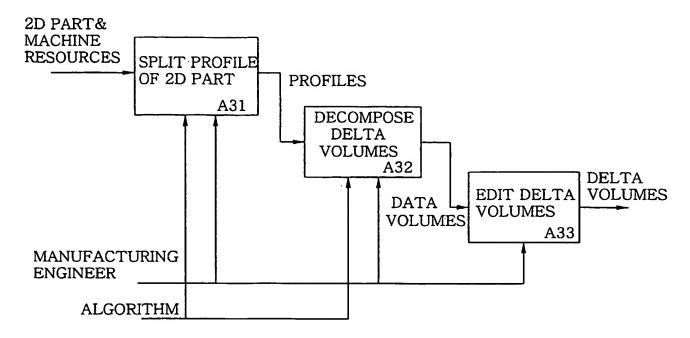


FIG. 42

